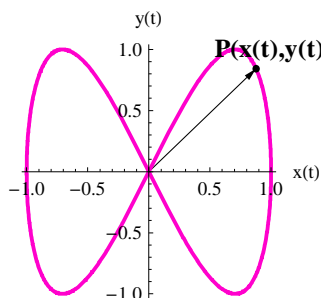


## 4

# REPRESENTACIÓN DE CURVAS EN FORMA PARAMÉTRICA

## 4.1. Parametrización de curvas en el plano

Una curva en forma paramétrica es la representación gráfica, en un sistema de ejes coordenados rectangulares OXY, de los pares  $(x(t), y(t))$  en el plano cartesiano OXY, donde  $t$  pertenece al dominio de  $x(t)$  y de  $y(t)$ .



### ▼ ParametricPlot[ ]

? ParametricPlot

`ParametricPlot[{f_x, f_y}, {u, u_min, u_max}]` generates a parametric plot of a curve with  $x$  and  $y$  coordinates  $f_x$  and  $f_y$  as a function of  $u$ .

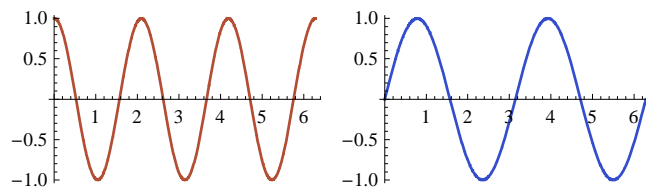
`ParametricPlot[{{f_x, f_y}, {g_x, g_y}, ...}, {u, u_min, u_max}]` plots several parametric curves.

`ParametricPlot[{f_x, f_y}, {u, u_min, u_max}, {v, v_min, v_max}]` plots a parametric region.

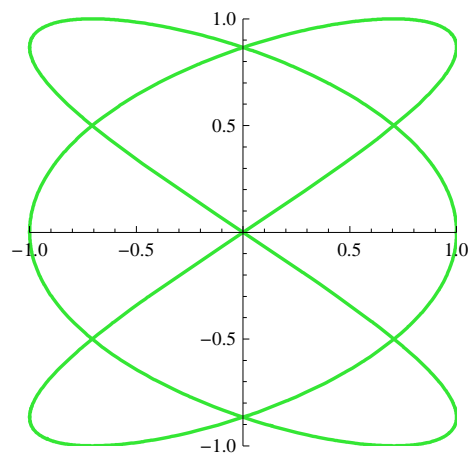
`ParametricPlot[{{f_x, f_y}, {g_x, g_y}, ...}, {u, u_min, u_max}, {v, v_min, v_max}]` plots several parametric regions. >>

```
r[t_] = {x[t_], y[t_]} = {Cos[3 * t], Sin[2 * t]};
```

```
GraphicsArray[
  {Plot[x[t], {t, 0, 2 * Pi}, PlotStyle -> {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],
  Plot[y[t], {t, 0, 2 * Pi}, PlotStyle -> {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}]}
```



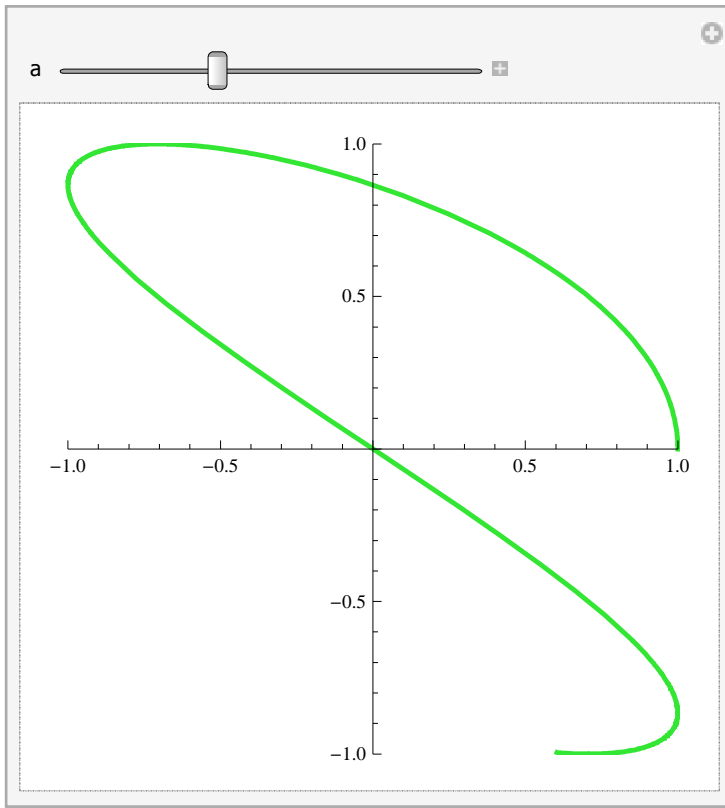
```
ParametricPlot[{Cos[3 * t], Sin[2 * t]}, {t, 0, 2 * Pi},
  PlotStyle -> {RGBColor[0.2, 0.9, 0.2], Thickness[0.008]}, PlotRange -> {{-1, 1}, {-1, 1}}
```



### ▼ Manipulate[ ]

Con este comando podemos ver como se dibuja la gráfica cuando recorremos el parámetro  $t$ .

```
Manipulate[ParametricPlot[{Cos[3 * t], Sin[2 * t]},  
  {t, 0, a}, PlotStyle -> {RGBColor[0.2, 0.9, 0.2], Thickness[0.008]},  
  PlotRange -> {{-1, 1}, {-1, 1}}, {a, 0.2, 2 * Pi}]
```



## 4.2. Parametrización de curvas dadas en forma explícita

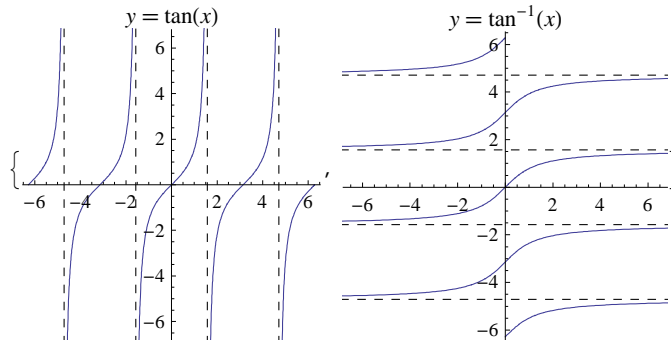
Dada una función  $y = f(x)$  definida de forma explícita, siempre se puede parametrizar en la forma

$$x(t) = x(t)$$

$$y(t) = f(x(t))$$

## ★ Ejemplo 1

```
{ParametricPlot[{u, Tan[u]}, {u, -2 Pi, 2 Pi},
  ExclusionsStyle -> Dashed, Exclusions -> {Cos[u] == 0}, PlotLabel -> y == Tan[x]],
ParametricPlot[{Tan[u], u}, {u, -2 Pi, 2 Pi}, ExclusionsStyle -> Dashed,
  Exclusions -> {Cos[u] == 0}, PlotLabel -> y == ArcTan[x]]}
```



## 4.3. Parametrización de curvas dadas en forma implícita

Dada una curva definida de forma implícita, siempre se puede parametrizar en la forma

$$x(t) = x(t)$$

$$y(t) = y, \text{ solución de la ecuación } f(x(t), y) = 0$$

### ▼ Parametrización de una circunferencia de centro (a,b) y radio r

$$\text{cir} = (x - a)^2 + (y - b)^2 = r^2$$

$$(-a + x)^2 + (-b + y)^2 = r^2$$

$$\mathbf{x}[t\_ ] = \mathbf{a} + \mathbf{r} * \text{Cos}[t]$$

$$a + r \text{Cos}[t]$$

`Solve[cir, y] /. x -> x[t] // Simplify`

$$\left\{ \left\{ y \rightarrow b - \sqrt{r^2 \text{Sin}[t]^2} \right\}, \left\{ y \rightarrow b + \sqrt{r^2 \text{Sin}[t]^2} \right\} \right\}$$

$$\text{circulo}[t\_ , a\_ , b\_ , r\_ ] = \{\mathbf{x}[t\_ ], \mathbf{y}[t\_ ]\} = \{\mathbf{a} + \mathbf{r} * \text{Sin}[t], \mathbf{b} + \mathbf{r} * \text{Cos}[t]\}$$

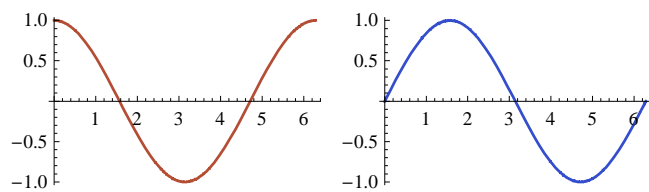
$$\{a + r \text{Sin}[t], b + r \text{Cos}[t]\}$$

### ▼ Parametrización de circunferencias con centro en el origen y radio r

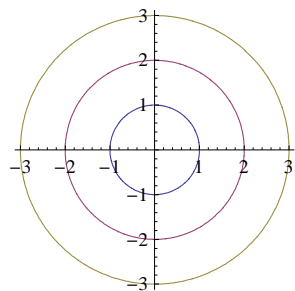
#### ★ Primera parametrización con orientación positiva

$$\mathbf{r}[t\_ ] = \{\mathbf{x}[t\_ ], \mathbf{y}[t\_ ]\} = \{\text{Cos}[t], \text{Sin}[t]\};$$

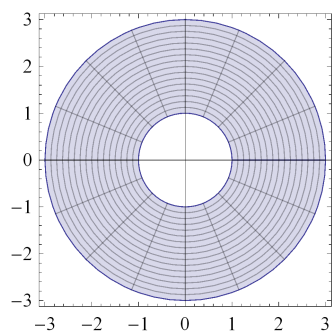
```
GraphicsArray[  
  {Plot[Cos[t], {t, 0, 2 * Pi}, PlotStyle -> {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],  
  Plot[Sin[t], {t, 0, 2 * Pi}, PlotStyle -> {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}]}
```

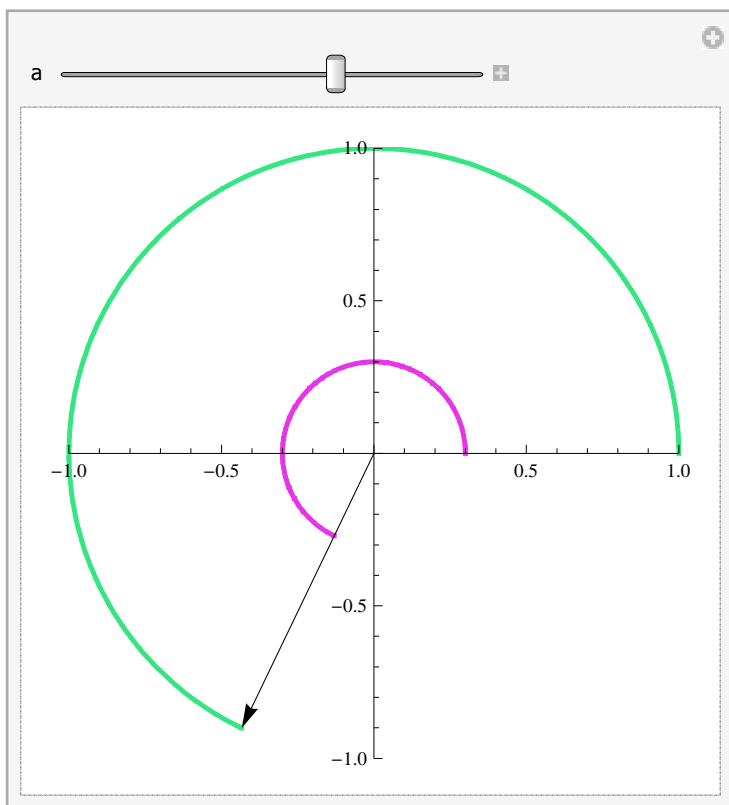


```
ParametricPlot[Evaluate[Table[{i Cos[u], i Sin[u]}, {i, 1, 3}], {u, 0, 2 Pi}]
```



```
ParametricPlot[{i Cos[u], i Sin[u]}, {i, 1, 3}, {u, 0, 2 Pi}]
```

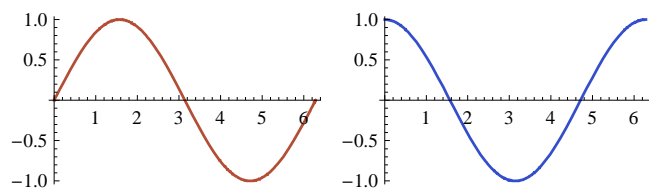


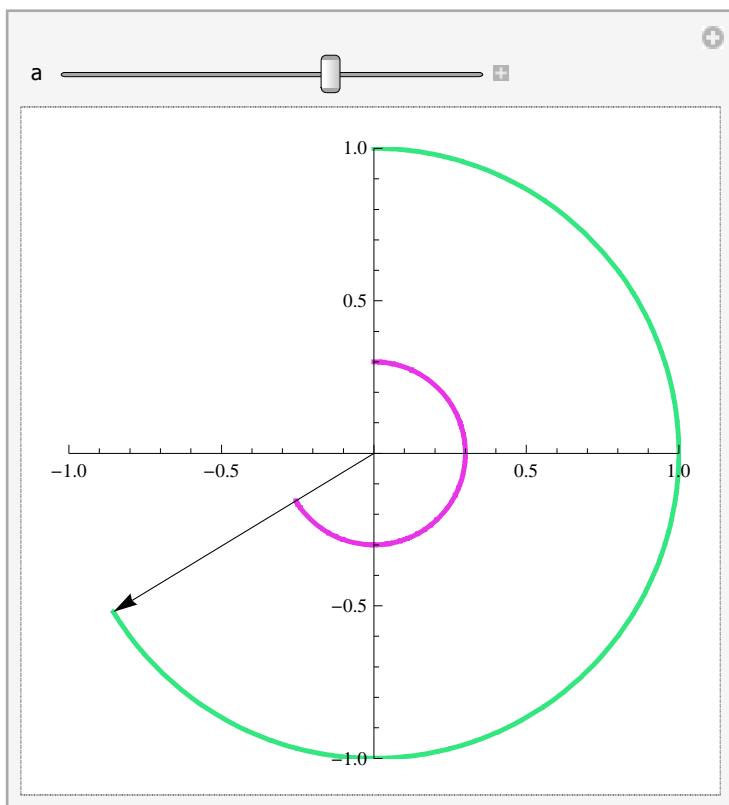


★ Segunda parametrización: en el sentido de las agujas del reloj

$r[t_] = \{x[t_], y[t_]\} = \{\text{Cos}[t], \text{Sin}[2t]\};$

```
GraphicsArray[
  {Plot[Sin[t], {t, 0, 2 * Pi}, PlotStyle -> {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],
   Plot[Cos[t], {t, 0, 2 * Pi}, PlotStyle -> {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}]}
```



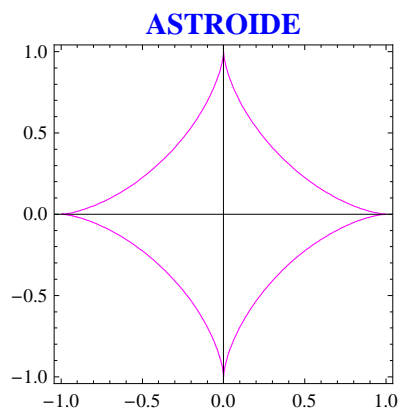


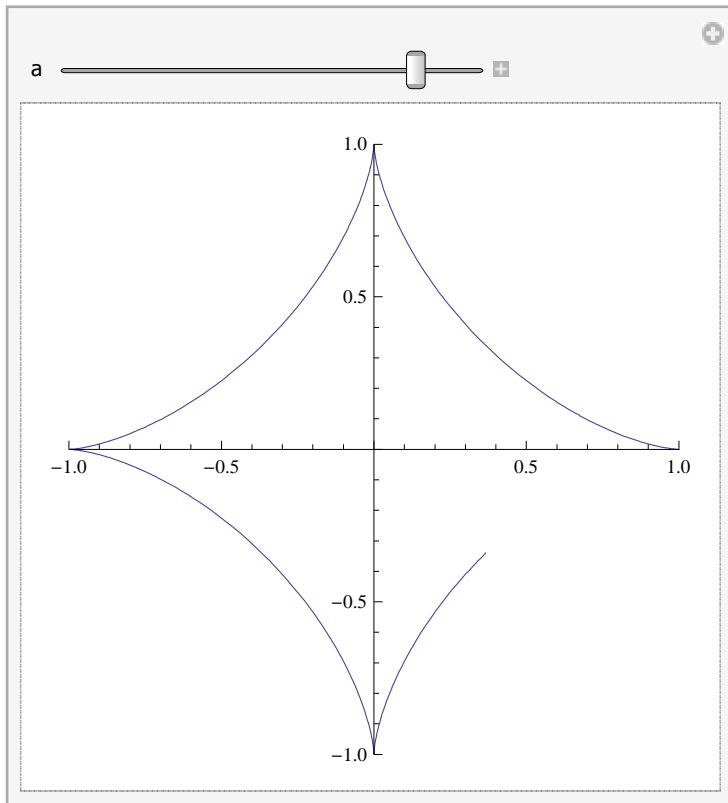
### ▼ Astroide

```
Clear[a]
```

```
astroide[t_, a_] = {a * Cos[t]^3, a * Sin[t]^3};
```

```
ParametricPlot[{Cos[t]^3, Sin[t]^3}, {t, 0, 2 π}, AspectRatio → Automatic,  
PlotStyle → Flatten[Table[RGBColor[a, 0, c], {a, 0, 1}, {c, 0, 1}]],  
PlotLabel → Style["ASTROIDE", Bold, Blue, 14], Frame → True]
```



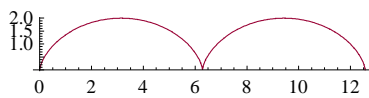


### ▼ Cicloide

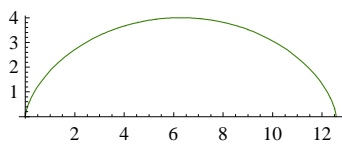
```
cicloide[t_, a_] = a * {t - Sin[t], 1 - Cos[t]}
```

```
{a (t - Sin[t]), a (1 - Cos[t])}
```

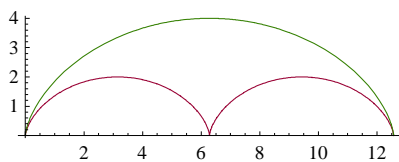
```
c1 = ParametricPlot[{cicloide[t, 1]}, {t, 0, 4 * Pi}, PlotStyle -> RGBColor[0.6, 0, 0.2]]
```



```
c2 = ParametricPlot[{cicloide[t, 2]}, {t, 0, 2 * Pi}, PlotStyle -> RGBColor[0.2, 0.5, 0]]
```



```
Show[{c1, c2}, PlotRange -> {0, 4}]
```

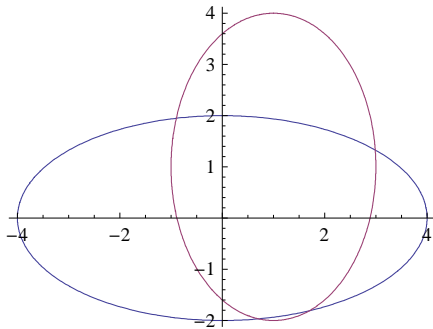


### ▼ Elipse

```
elipse[t_, a_, b_, c_, d_] = {a * Sin[t], b * Cos[t]} + {c, d};
```



```
ParametricPlot[Evaluate[{ellipse[t, 4, 2, 0, 0], ellipse[t, 2, 3, 0, 0] + {1, 1}},
  {t, 0, 2 Pi}, AspectRatio -> Automatic]
```



## 4.4. Parametrización de curvas dadas en forma polar

Si la curva viene dada en forma polar por la función  $r=r(t)$ , se puede escribir en forma paramétrica como

$$x(t) = r(t) \cos t$$

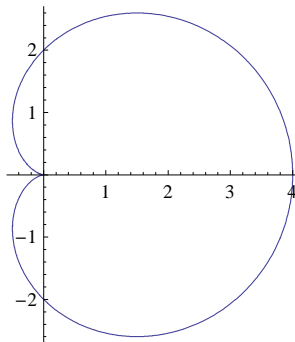
$$y(t) = r(t) \sin t$$

### ▼ Elipse

```
Clear["Global`*"]
```

```
cardioide[t_, a_] = {a * Cos[t] * (1 + Cos[t]), a * Sin[t] (1 + Cos[t])};
```

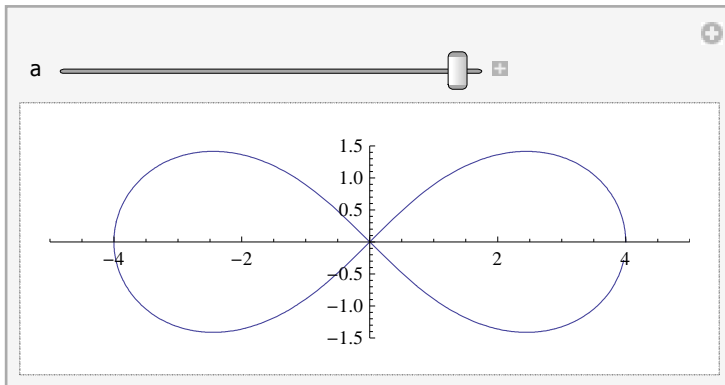
```
ParametricPlot[cardioide[t, 2], {t, 0, 2 Pi}]
```



### ▼ Lemniscata

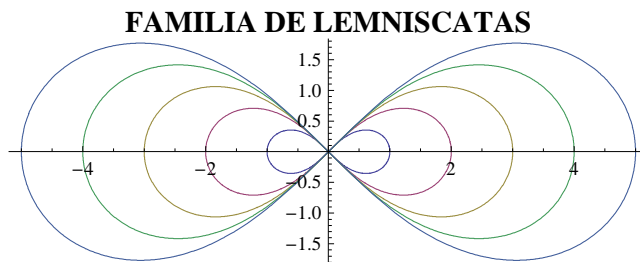
```
lemniscata[t_, a_] = {a * Cos[t] / (1 + Sin[t]^2), a * Sin[t] * Cos[t] / (1 + Sin[t]^2)};
```

```
Manipulate[
  ParametricPlot[{4 * Cos[t] / (1 + Sin[t]^2), 4 * Sin[t] * Cos[t] / (1 + Sin[t]^2)}, {t, 0, a},
    AspectRatio -> Automatic, PlotRange -> {{-5, 5}, {-1.5, 1.5}}, {a, 0.01, 2 * Pi, 0.1}]
```



```
lemniscata[t_, a_] = {a * Cos[t] / (1 + Sin[t]^2), a * Sin[t] * Cos[t] / (1 + Sin[t]^2)};
```

```
ParametricPlot[Evaluate[Table[lemniscata[t, a], {a, 1, 5}]], {t, 0, 2 * Pi},
  AspectRatio -> Automatic, PlotLabel -> Style["FAMILIA DE LEMNISCATAS", Bold, 14]]
```

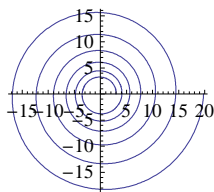


### ▼ Espiral Logarítmica

```
espirallog[t_, a_, b_] = {a * E^(b * t) * Cos[t], a * E^(b * t) * Sin[t]}
```

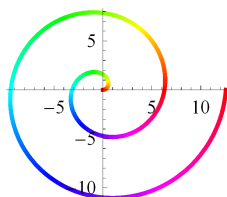
```
{a eb t Cos[t], a eb t Sin[t]}
```

```
ParametricPlot[espirallog[t, 3, 0.05], {t, 0, 12 Pi}, AspectRatio -> Automatic]
```

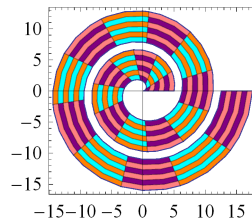


### ▼ Espiral de Arquímedes

```
ParametricPlot[{u Cos[u], u Sin[u]}, {u, 0, 4 Pi}, PlotStyle -> Thick,
  ColorFunction -> Function[{x, y, u, v}, Hue[u / (2 Pi)]], ColorFunctionScaling -> False]
```



```
ParametricPlot[{(v + u) Cos[u], (v + u) Sin[u]}, {u, 0, 4 Pi},
  {v, 0, 5}, Mesh -> {20, 5}, MeshShading -> {{Purple, Cyan}, {Pink, Orange}}]
```



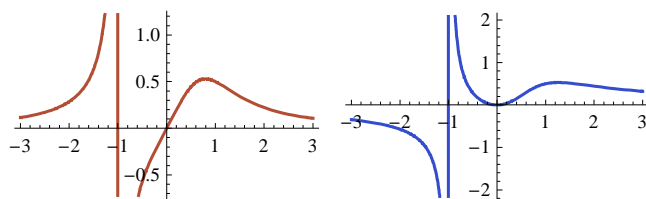
## 4.5. Curvas con ramas infinitas

### ▼ Folium de Descartes

#### ★ Definimos la parametrización

$$r[t_] = \{x[t_], y[t_]\} = \left\{ \frac{t}{1+t^3}, \frac{t^2}{1+t^3} \right\};$$

```
GraphicsArray[
  {Plot[x[t], {t, -3, 3}, PlotStyle -> {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],
  Plot[y[t], {t, -3, 3}, PlotStyle -> {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}}]
```



#### ★ Analizamos los puntos de corte y las ramas infinitas

##### Puntos de corte

```
Solve[x[t] == 0, t]
```

```
{{t -> 0}}
```

```
Solve[y[t] == 0, t]
```

```
{{t -> 0}, {t -> 0}}
```

##### Ramas Infinitas

```
to = -1;
```

```
Limit[x[t], t -> to]
```

```
Limit[y[t], t -> to]
```

```
-∞
```

```
∞
```

```
to = -∞;
```

```
Limit[x[t], t -> to]
```

```
Limit[y[t], t -> to]
```

```
0
```

```
0
```

```

to = ∞;
Limit[x[t], t → to]
Limit[y[t], t → to]

0
0

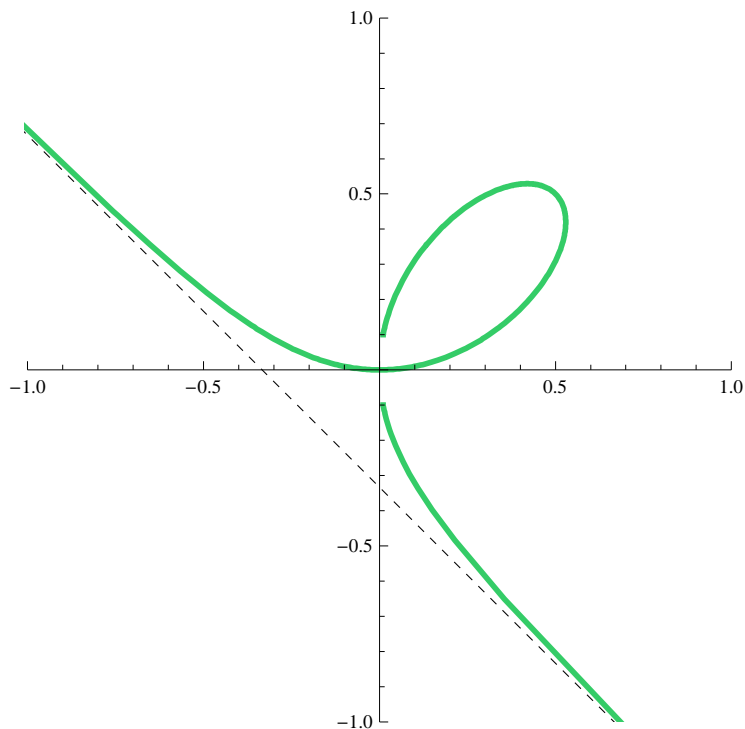
```

### ★ Gráfica en coordenadas paramétricas

```

ParametricPlot[{{ $\frac{t}{1+t^3}$ ,  $\frac{t^2}{1+t^3}$ }, {t, -10, 10},
ExclusionsStyle → Dashed, Exclusions → {1 + t3 = 0},
PlotStyle → {RGBColor[0.2, 0.8, 0.4], Thickness[0.008]}, PlotRange → {{-1, 1}, {-1, 1}}]

```



### ▼ Función paramétrica con asíntota

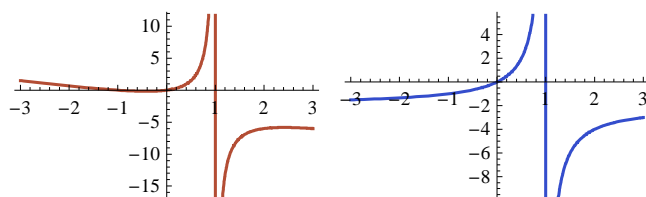
#### ★ Definimos la parametrización

$$r[t_] = \{x[t_], y[t_]\} = \left\{ \frac{t^2 + t}{1 - t}, \frac{2 * t}{1 - t} \right\};$$

```

GraphicsArray[
{Plot[x[t], {t, -3, 3}, PlotStyle → {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],
Plot[y[t], {t, -3, 3}, PlotStyle → {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}]}]

```



## ★ Analizamos los puntos de corte y las ramas infinitas

Puntos de corte

```
Solve[x[t] == 0, t]
```

```
{{t -> -1}, {t -> 0}}
```

```
Solve[y[t] == 0, t]
```

```
{{t -> 0}}
```

Ramas Infinitas

```
to = 1;
```

```
Limit[x[t], t -> to]
```

```
Limit[y[t], t -> to]
```

```
-∞
```

```
-∞
```

```
to = -∞;
```

```
Limit[x[t], t -> to]
```

```
Limit[y[t], t -> to]
```

```
∞
```

```
-2
```

```
to = ∞;
```

```
Limit[x[t], t -> to]
```

```
Limit[y[t], t -> to]
```

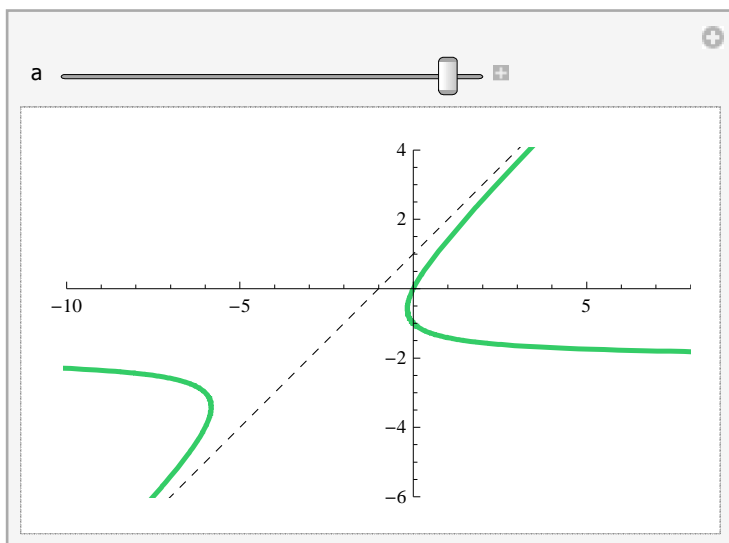
```
-∞
```

```
-2
```

## ★ Gráfica en coordenadas paramétricas

```
ParametricPlot[{{ $\frac{t^2 + t}{1 - t}$ ,  $\frac{2 * t}{1 - t}$ }, {t, -10, 10}, ExclusionsStyle -> Dashed,
  Exclusions -> {t == 1}, PlotStyle -> {RGBColor[0.2, 0.8, 0.4], Thickness[0.008]},
  PlotRange -> {{-10, 8}, {-6, 4}}];
```

```
Manipulate[ParametricPlot[{ $\frac{t^2 + t}{1 - t}$ ,  $\frac{2 * t}{1 - t}$ }, {t, -10, a}, ExclusionsStyle -> Dashed,
  Exclusions -> {t == 1}, PlotStyle -> {RGBColor[0.2, 0.8, 0.4], Thickness[0.008]},
  PlotRange -> {{-10, 8}, {-6, 4}}, {a, -9.95, 10, 0.05}]
```



## 4.6. Curvas parametrizadas en 3D

### ▼ ParametricPlot3D

#### Helicoide

```
ParametricPlot3D[{Sin[u], Cos[u], u / 10}, {u, 0, 20},
  PlotStyle -> Directive[Red, Thick], ColorFunction -> "DarkRainbow"]
```

