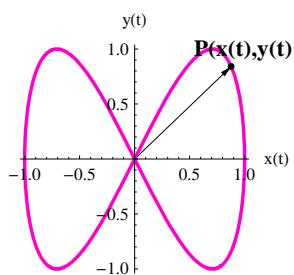


4

REPRESENTATION OF CURVES IN PARAMETRIC FORM

4.1. Parametrization of curves in the plane

Given a curve in parametric form, its graphical representation in a rectangular bidimensional system OXY is formed by the points $(x(t), y(t))$, being the parameter t in the domains of the functions $x(t)$ and $y(t)$.

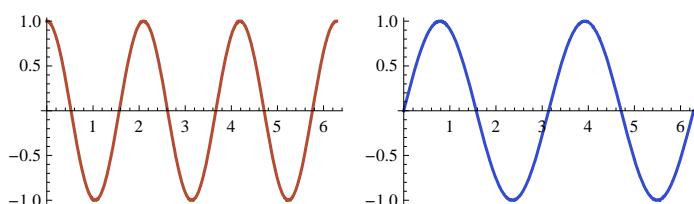


▼ ParametricPlot[]

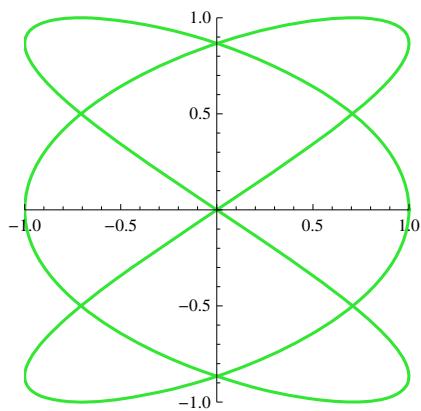
? ParametricPlot

ParametricPlot[$\{f_x, f_y\}$, $\{u, u_{min}, u_{max}\}$] generates a parametric plot of a curve with x and y coordinates f_x and f_y as a function of u .
 ParametricPlot[$\{\{f_x, f_y\}, \{g_x, g_y\}, \dots\}, \{u, u_{min}, u_{max}\}$] plots several parametric curves.
 ParametricPlot[$\{f_x, f_y\}, \{u, u_{min}, u_{max}\}, \{v, v_{min}, v_{max}\}$] plots a parametric region.
 ParametricPlot[$\{\{f_x, f_y\}, \{g_x, g_y\}, \dots\}, \{u, u_{min}, u_{max}\}, \{v, v_{min}, v_{max}\}$] plots several parametric regions. >>

```
Clear["Global`*"]
r[t_] = {x[t], y[t]} = {Cos[3*t], Sin[2*t]};
GraphicsArray[
{Plot[x[t], {t, 0, 2*Pi}, PlotStyle -> {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],
 Plot[y[t], {t, 0, 2*Pi}, PlotStyle -> {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}]}]
```



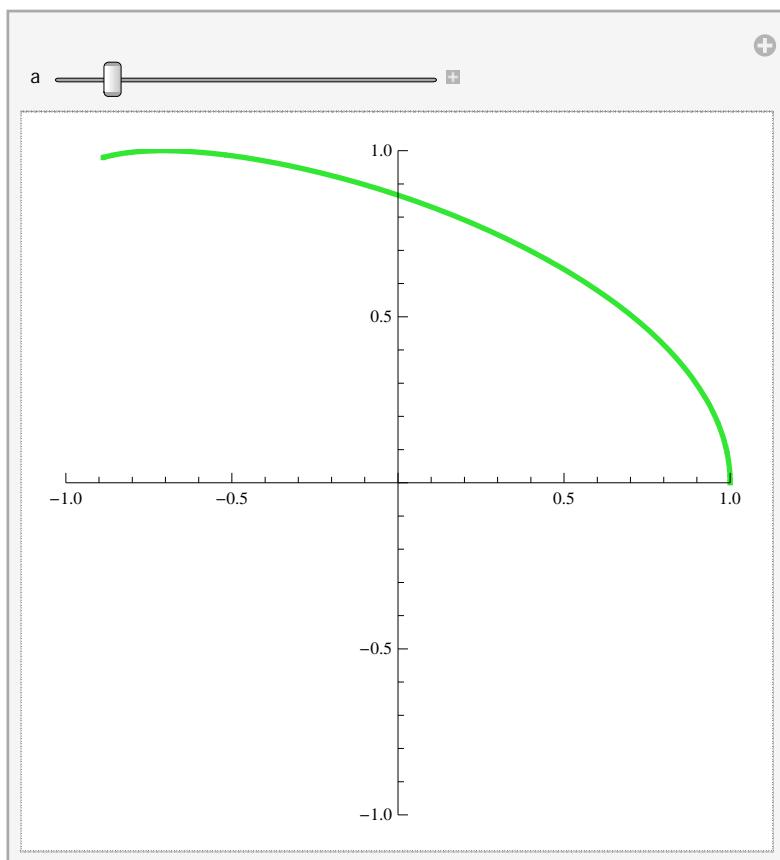
```
ParametricPlot[{Cos[3*t], Sin[2*t]}, {t, 0, 2*Pi},
PlotStyle -> {RGBColor[0.2, 0.9, 0.2], Thickness[0.008]}, PlotRange -> {{-1, 1}, {-1, 1}}]
```



▼ Manipulate[]

This command makes possible to see how the graphic is represented as the parameter "t" takes different values.

```
Manipulate[ParametricPlot[{Cos[3*t], Sin[2*t]},
{t, 0, a}, PlotStyle -> {RGBColor[0.2, 0.9, 0.2], Thickness[0.008]},
PlotRange -> {{-1, 1}, {-1, 1}}], {a, 0.2, 2*Pi}]
```



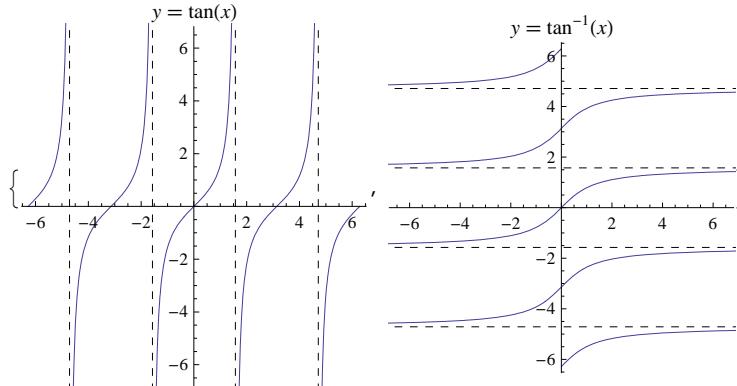
4.2. Parametrization of curves given in explicit form

Given the function $y = f(x)$, it is always possible to parametrize it as:

$$\begin{aligned}x(t) &= x(t) \\y(t) &= f(x(t))\end{aligned}$$

★ Example 1

```
{ParametricPlot[{u, Tan[u]}, {u, -2 Pi, 2 Pi},
  ExclusionsStyle → Dashed, Exclusions → {Cos[u] == 0}, PlotLabel → y == Tan[x]],
ParametricPlot[{Tan[u], u}, {u, -2 Pi, 2 Pi}, ExclusionsStyle → Dashed,
  Exclusions → {Cos[u] == 0}, PlotLabel → y == ArcTan[x]]}
```



4.3. Parametrization of curves given in implicit form

Given an implicit function, it is always possible to parametrize it as:

$$x(t) = x(t)$$

$y(t) = y$, being "y" the solution of the equation $f(x(t), y) = 0$

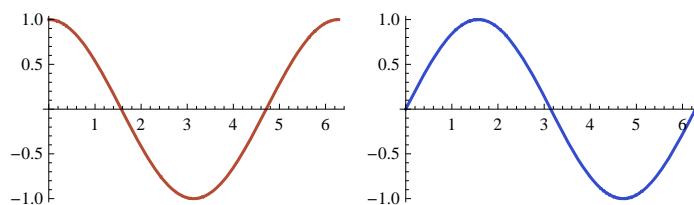
▼ Parametrization of a circumference of centre (a,b) and radius r

```
cir1 = (x - a)^2 + (y - b)^2 == r^2
(-a + x)^2 + (-b + y)^2 == r^2
x[t_] = a + r * Cos[t]
a + r Cos[t]
Solve[cir1, y] /. x → x[t] // Simplify
{{y → b - Sqrt[r^2 Sin[t]^2]}, {y → b + Sqrt[r^2 Sin[t]^2]}}
circ[t_, a_, b_, r_] = {x[t_], y[t_]} = {a + r * Sin[t], b + r * Cos[t]}
{a + r Sin[t], b + r Cos[t]}
```

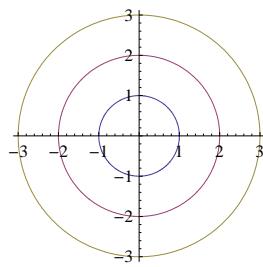
▼ Parametrization of a circumference of centre $(0,0)$ and radius r

★ First parametrization of positive orientation

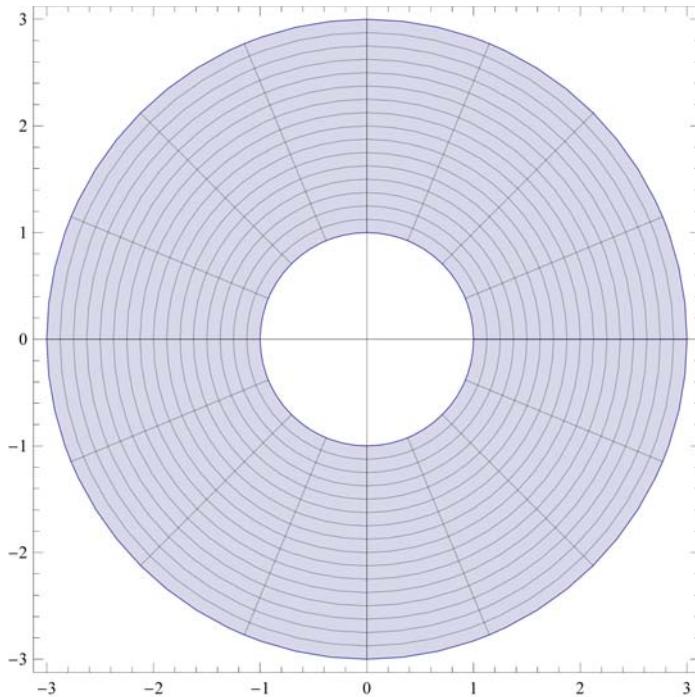
```
r[t_] = {x[t_], y[t_]} = {Cos[t], Sin[t]};
GraphicsArray[
{Plot[Cos[t], {t, 0, 2 * Pi}, PlotStyle → {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],
 Plot[Sin[t], {t, 0, 2 * Pi}, PlotStyle → {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}]}]
```



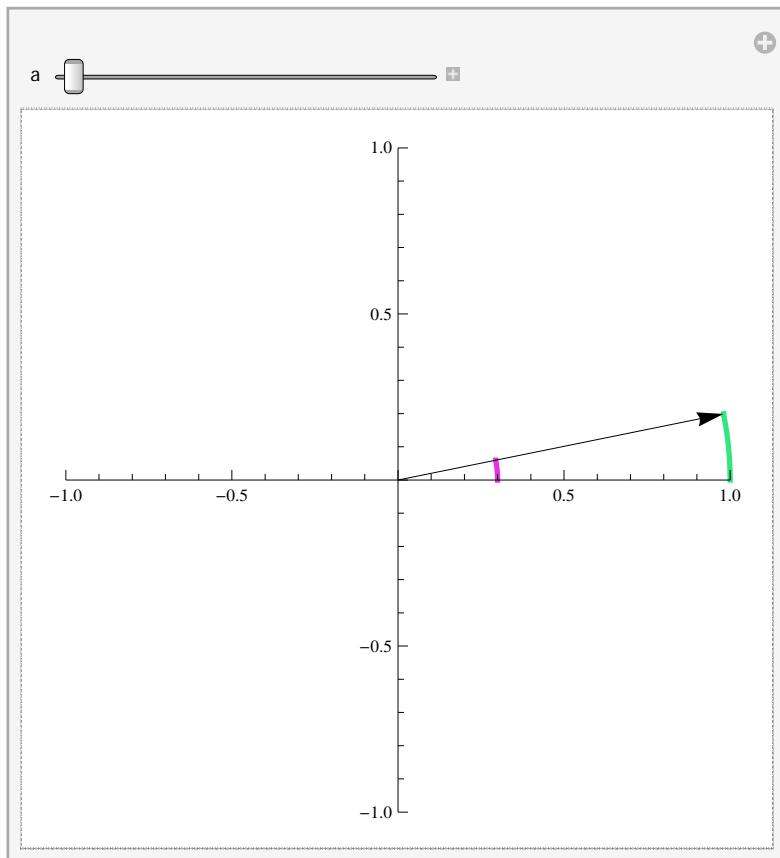
```
ParametricPlot[Evaluate[Table[{i Cos[u], i Sin[u]}, {i, 1, 3}]], {u, 0, 2 Pi}]
```



```
ParametricPlot[{i Cos[u], i Sin[u]}, {i, 1, 3}, {u, 0, 2 Pi}]
```

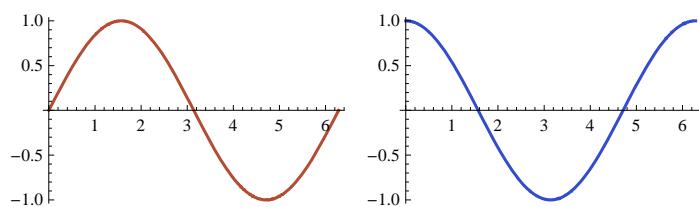


```
Manipulate[Show[ParametricPlot[{{Cos[t], Sin[t]}, {0.3 * Cos[t], 0.3 * Sin[t]}}, {t, 0, a}, PlotStyle -> {{RGBColor[0.2, 0.9, 0.5], Thickness[0.008]}, {RGBColor[0.9, 0.2, 0.9], Thickness[0.008]}}, PlotRange -> {{-1, 1}, {-1, 1}}], Graphics[Arrow[{{0, 0}, {Cos[a], Sin[a]}}]]], {a, 0.2, 2 * Pi}]
```

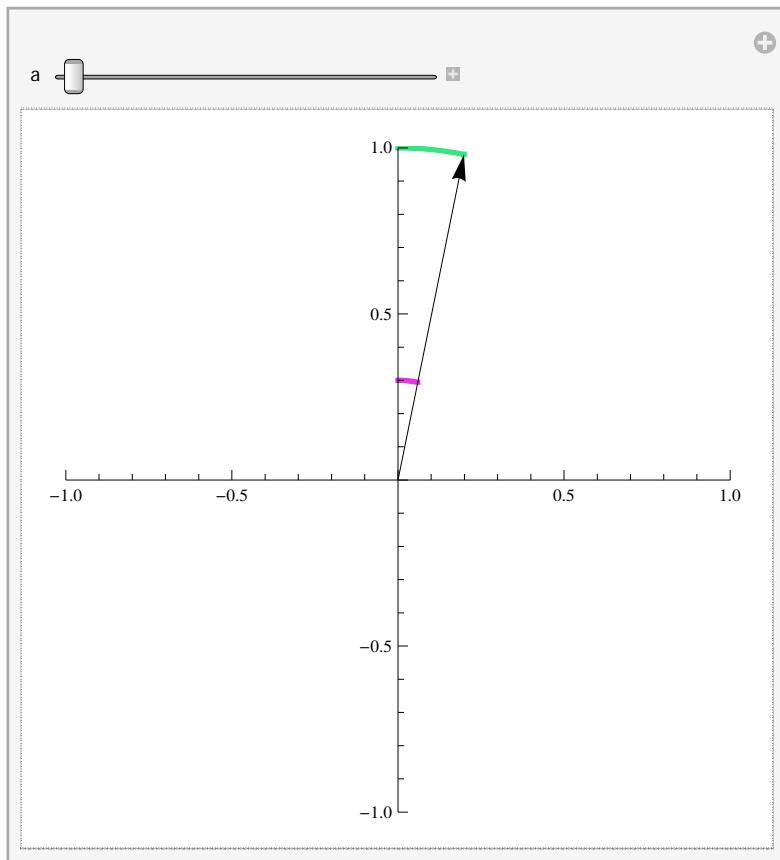


★ Second parametrization in clockwise direction

```
r[t_] = {x[t_], y[t_]} = {Cos[t], Sin[2 t]};  
GraphicsArray[{  
  Plot[Sin[t], {t, 0, 2 * Pi}, PlotStyle -> {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],  
  Plot[Cos[t], {t, 0, 2 * Pi}, PlotStyle -> {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}]}]
```

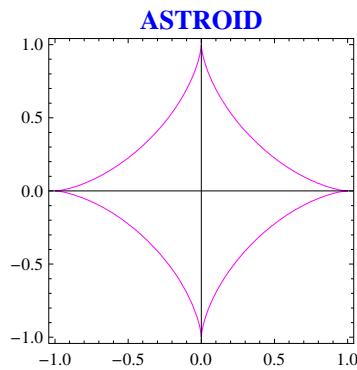


```
Manipulate[Show[ParametricPlot[{{Sin[t], Cos[t]}, {0.3 * Sin[t], 0.3 * Cos[t]}}, {t, 0, a}, PlotStyle -> {{RGBColor[0.2, 0.9, 0.5], Thickness[0.008]}, {RGBColor[0.9, 0.2, 0.9], Thickness[0.008]}}, PlotRange -> {{-1, 1}, {-1, 1}}], Graphics[Arrow[{{0, 0}, {Sin[a], Cos[a]}}]]], {a, 0.2, 2 * Pi}]
```

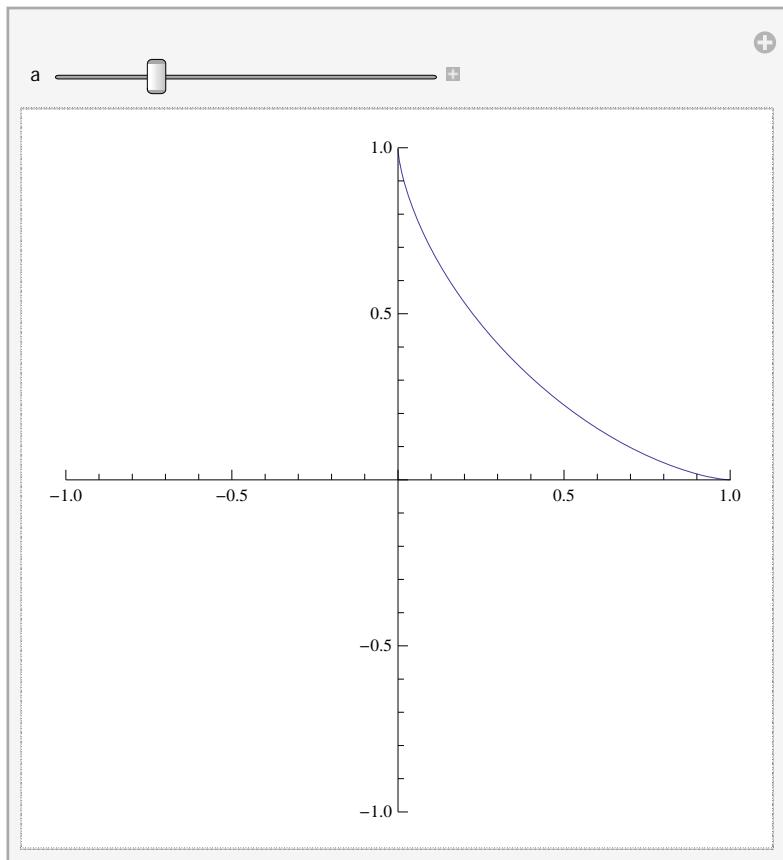


▼ Astroid

```
Clear[a]
astroid[t_, a_] = {a * Cos[t]^3, a * Sin[t]^3};
ParametricPlot[{Cos[t]^3, Sin[t]^3}, {t, 0, 2 \pi}, AspectRatio -> Automatic,
PlotStyle -> Flatten[Table[RGBColor[a, 0, c], {a, 0, 1}, {c, 0, 1}]], PlotLabel -> Style["ASTROID", Bold, Blue, 14], Frame -> True]
```

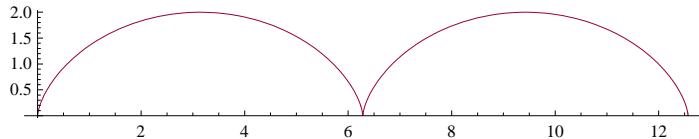


```
Manipulate[ParametricPlot[{Cos[t]^3, Sin[t]^3}, {t, 0, a},
  AspectRatio -> Automatic, PlotRange -> {{-1, 1}, {-1, 1}}], {a, 0.01, 2 * Pi, 0.1}]
```

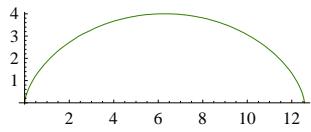


▼ Cycloid

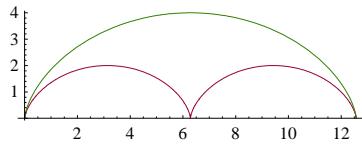
```
cycloid[t_, a_] = a * {t - Sin[t], 1 - Cos[t]}
{a (t - Sin[t]), a (1 - Cos[t])}
c1 = ParametricPlot[{cycloid[t, 1]}, {t, 0, 4 * Pi}, PlotStyle -> RGBColor[0.6, 0, 0.2]]
```



```
c2 = ParametricPlot[{cycloid[t, 2]}, {t, 0, 2 * Pi}, PlotStyle -> RGBColor[0.2, 0.5, 0]]
```

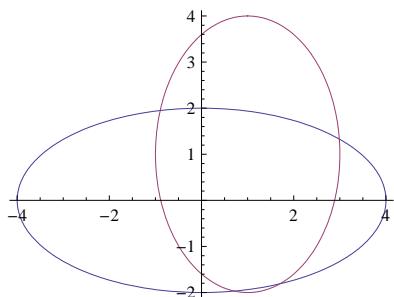


```
Show[{c1, c2}, PlotRange -> {0, 4}]
```



▼ Ellipse

```
Clear["Global`*"]
ellipse[t_, a_, b_, c_, d_] = {a * Sin[t], b * Cos[t]} + {c, d};
ParametricPlot[Evaluate[{ellipse[t, 4, 2, 0, 0], ellipse[t, 2, 3, 0, 0] + {1, 1}}],
{t, 0, 2 Pi}, AspectRatio -> Automatic]
```



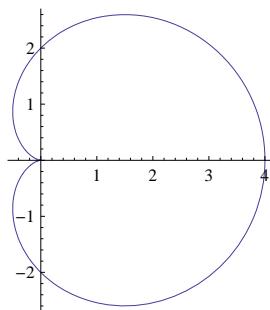
4.4. Parametrization of curves given in polar form

Given the function $r=r(t)$, it is always possible to parametrize it as:

$$\begin{aligned}x(t) &= r(t) \cos t \\y(t) &= r(t) \sin t\end{aligned}$$

▼ Cardioid

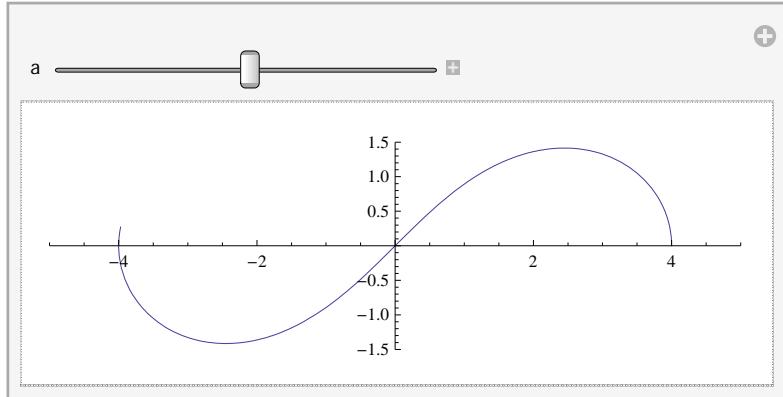
```
Clear["Global`*"]
cardioid[t_, a_] = {a * Cos[t] * (1 + Cos[t]), a * Sin[t] * (1 + Cos[t])};
ParametricPlot[cardioid[t, 2], {t, 0, 2 Pi}]
```



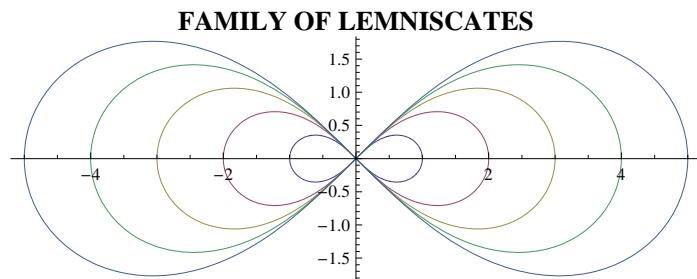
▼ Lemniscate

```
lemniscate[t_, a_] = {a * Cos[t] / (1 + Sin[t]^2), a * Sin[t] * Cos[t] / (1 + Sin[t]^2)};
```

```
Manipulate[
ParametricPlot[{4 * Cos[t] / (1 + Sin[t]^2), 4 * Sin[t] * Cos[t] / (1 + Sin[t]^2)}, {t, 0, a},
AspectRatio -> Automatic, PlotRange -> {{-5, 5}, {-1.5, 1.5}}], {a, 0.01, 2 * Pi, 0.1}]
```

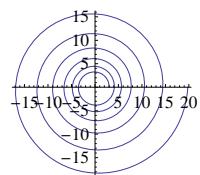


```
lemniscate[t_, a_] = {a * Cos[t] / (1 + Sin[t]^2), a * Sin[t] * Cos[t] / (1 + Sin[t]^2)};
ParametricPlot[Evaluate[Table[lemniscate[t, a], {a, 1, 5}]], {t, 0, 2 \u03c0},
AspectRatio -> Automatic, PlotLabel -> Style["FAMILY OF LEMNISCATES", Bold, 14]]
```



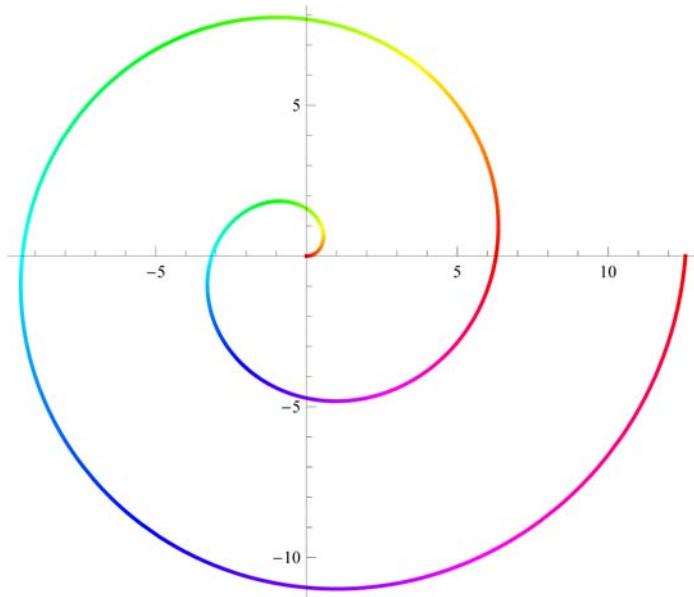
▼ Logarithmic spiral

```
spiralog[t_, a_, b_] = {a * E^(b * t) * Cos[t], a * E^(b * t) * Sin[t]};
{a e^{bt} Cos[t], a e^{bt} Sin[t]}
ParametricPlot[spiralog[t, 3, 0.05], {t, 0, 12 Pi}, AspectRatio -> Automatic]
```

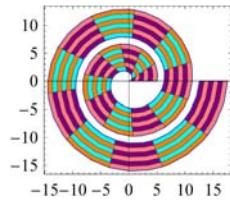


▼ Archimedes spiral

```
ParametricPlot[{u Cos[u], u Sin[u]}, {u, 0, 4 Pi}, PlotStyle -> Thick,
ColorFunction -> Function[{x, y, u, v}, Hue[u / (2 Pi)]], ColorFunctionScaling -> False]
```



```
ParametricPlot[{(v + u) Cos[u], (v + u) Sin[u]}, {u, 0, 4 Pi},
{v, 0, 5}, Mesh -> {20, 5}, MeshShading -> {{Purple, Cyan}, {Pink, Orange}}]
```



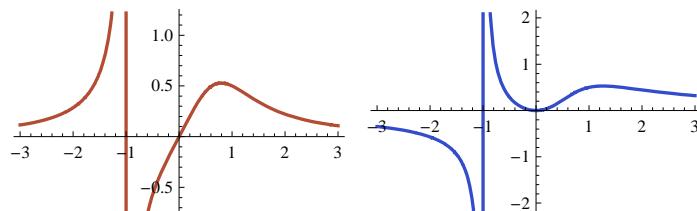
4.5. Curves of infinite branches

▼ Descartes folium

★ Parametrization

$$\mathbf{r}[t] = \{x[t], y[t]\} = \left\{ \frac{t}{1+t^3}, \frac{t^2}{1+t^3} \right\};$$

```
GraphicsArray[
{Plot[x[t], {t, -3, 3}, PlotStyle -> {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],
Plot[y[t], {t, -3, 3}, PlotStyle -> {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}]}]
```



★ Analysis of the cut points and infinite branches

Cut points

```
Solve[x[t] == 0, t]
{{t → 0}}
Solve[y[t] == 0, t]
{{t → 0}, {t → 0}}
```

Infinite branches

```
to = -1;
Limit[x[t], t → to]
Limit[y[t], t → to]

-∞
∞

to = -∞;
Limit[x[t], t → to]
Limit[y[t], t → to]

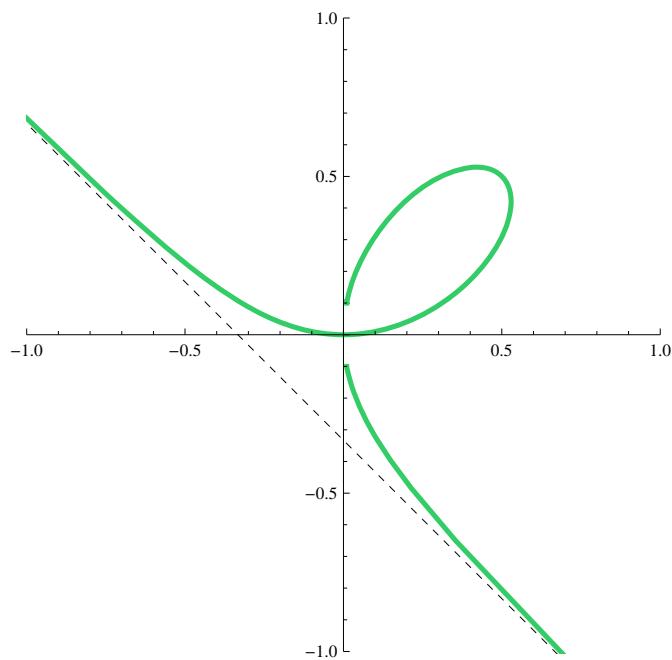
0
0

to = ∞;
Limit[x[t], t → to]
Limit[y[t], t → to]

0
0
```

★ Graph of the parametric coordinates function

```
ParametricPlot[{\frac{t}{1+t^3}, \frac{t^2}{1+t^3}}, {t, -10, 10},
ExclusionsStyle → Dashed, Exclusions → {1+t^3 == 0},
PlotStyle → {RGBColor[0.2, 0.8, 0.4], Thickness[0.008]}, PlotRange → {{-1, 1}, {-1, 1}}]
```

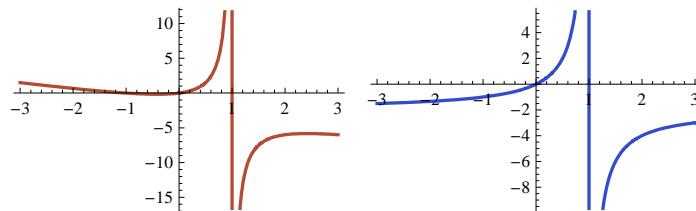


▼ Parametric function with asymptote

★ Parametrization

$$\mathbf{r}[t] = \{x[t], y[t]\} = \left\{ \frac{t^2 + t}{1 - t}, \frac{2 * t}{1 - t} \right\};$$

```
GraphicsArray[
{Plot[x[t], {t, -3, 3}, PlotStyle -> {RGBColor[0.7, 0.3, 0.2], Thickness[0.01]}],
 Plot[y[t], {t, -3, 3}, PlotStyle -> {RGBColor[0.2, 0.3, 0.8], Thickness[0.01]}]}]
```



★ Analysis of the cut points and infinite branches

Cut points

```
Solve[x[t] == 0, t]
{{t -> -1}, {t -> 0}}
Solve[y[t] == 0, t]
{{t -> 0}}
```

Infinite branches

```
to = 1;
Limit[x[t], t -> to]
Limit[y[t], t -> to]
-∞
-∞

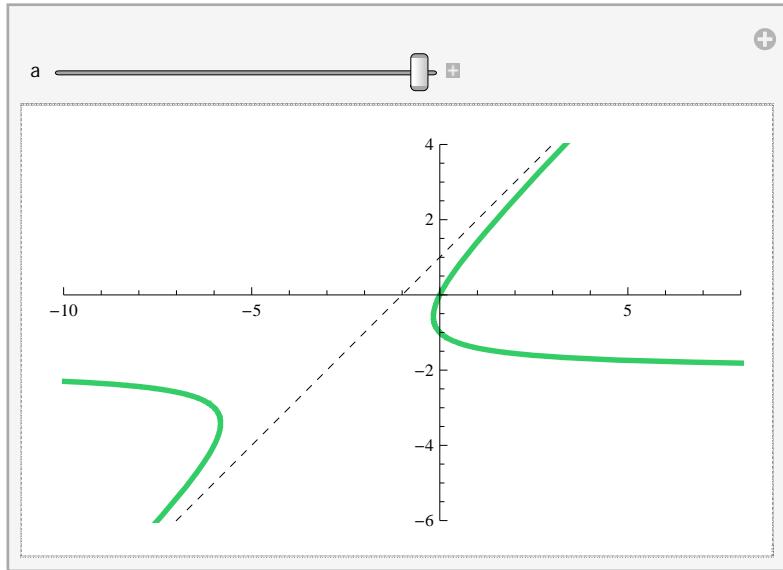
to = -∞;
Limit[x[t], t -> to]
Limit[y[t], t -> to]
∞
-2

to = ∞;
Limit[x[t], t -> to]
Limit[y[t], t -> to]
-∞
-2
```

★ Graph of the parametric coordinates function

```
ParametricPlot[{(t^2 + t)/(1 - t), (2 * t)/(1 - t)}, {t, -10, 10}, ExclusionsStyle -> Dashed,
Exclusions -> {t == 1}, PlotStyle -> {RGBColor[0.2, 0.8, 0.4], Thickness[0.008]},
PlotRange -> {{-10, 8}, {-6, 4}}];
```

```
Manipulate[ParametricPlot[\{\frac{t^2+t}{1-t}, \frac{2*t}{1-t}\}, {t, -10, a}, ExclusionsStyle -> Dashed,  
Exclusions -> {t == 1}, PlotStyle -> {RGBColor[0.2, 0.8, 0.4], Thickness[0.008]},  
PlotRange -> {{{-10, 8}, {-6, 4}}}], {a, -9.95, 10, 0.05}]
```



4.6. Graphs parametrized in 3D

▼ ParametricPlot3D

Helicoid

```
ParametricPlot3D[{Sin[u], Cos[u], u / 10}, {u, 0, 20},  
PlotStyle -> Directive[Red, Thick], ColorFunction -> "DarkRainbow"]
```

